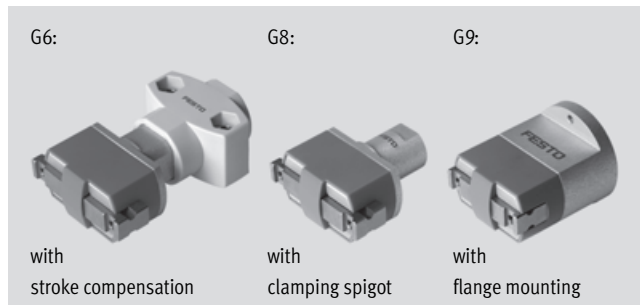


Parallel grippers HGPM, micro



Parallel grippers HGPM, micro

Key features



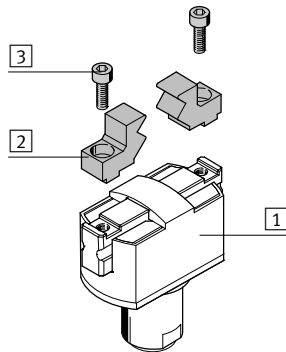
At a glance

- Compact, handy design
- With open or closed gripper jaws
- Versatility thanks to externally adaptable gripper fingers
- Wide range of options for attaching drive units
- With stroke compensation after installation
- Mounting options:
 - Clamping spigot
 - Flange mounting

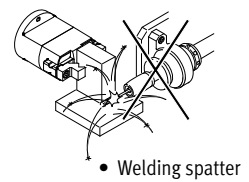
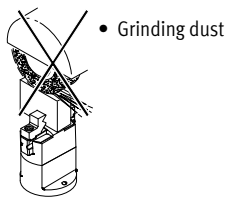
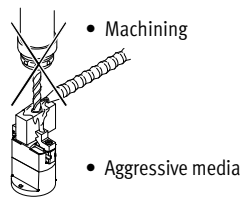
- - Note
 Sizing software
 Gripper selection
 → www.festo.com

Mounting options for external gripper fingers (customer-specific)

- 1 Parallel gripper
- 2 External gripper fingers
- 3 Mounting screws



- - Note
 Grippers are not suitable for the following, or for similar applications:



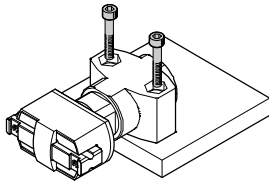
Parallel grippers HGPM, micro

Key features

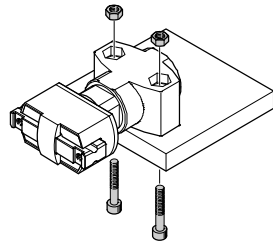


Mounting options

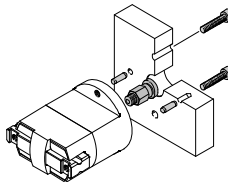
With through-holes



With through-holes, screws and retaining nuts

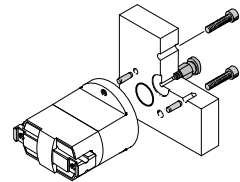


With flange mounting, screws and dowel pins



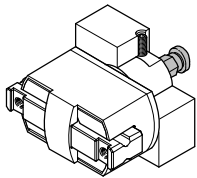
Direct air supply

Integrated air supply

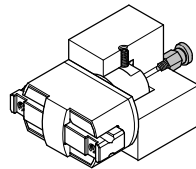


With set screw

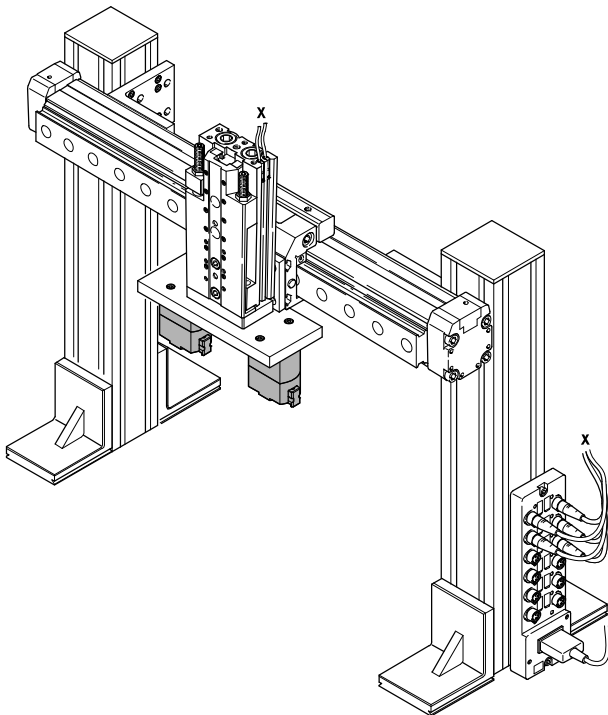
Direct air supply



Integrated air supply



System product for handling and assembly technology



	→ Page/Internet
Drives	drive
Grippers	gripper
Adapters	adapter kit
Basic mounting components	basic component
Installation components	installation component
Axes	axes
Motors	motor

Parallel grippers HGPM, micro

Type codes

HGPM – 12 – EO – G8

Type	
HGPM	Parallel gripper

Size	

Gripper jaw position	
EO	Open
EZ	Closed

Mounting options	
G6	With stroke compensation
G8	With clamping spigot
G9	With flange mounting

Parallel grippers HGPM, micro

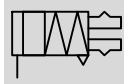
Technical data

Function

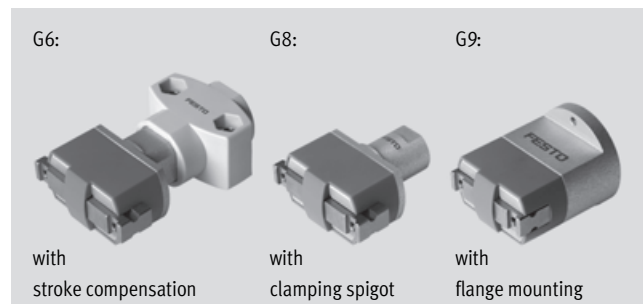
Single-acting
with open gripper jaws
HGPM-...-EO-G...



with closed gripper jaws
HGWM-...-EZ-G...



\varnothing - Size
8 ... 12 mm
 - | - Stroke
4 ... 6 mm



General technical data			
Size		8	12
Constructional design	Wedge-shaped drive		
Mode of operation	Single-acting		
Gripper function	Parallel		
Number of gripper jaws	2		
Max. weight force per external gripper finger ¹⁾	[N]	0.05	0.15
Resetting force ²⁾	Gripper jaws open	[N]	1.5
	Gripper jaws closed	[N]	2
Stroke per gripper jaw	[mm]	2	3
Pneumatic connection	M3		
Repetition accuracy ^{3) 4)}	[mm]	< 0.05	
Max. interchangeability	[mm]	0.4	
Max. operating frequency	[Hz]	4	
Centring precision ⁴⁾	[mm]	< \varnothing 0.15 (valid only for HGPM-...-G8 and HGPM-...-G9)	
Position sensing	Without		
Type of mounting	HGPM-...-E...-G6	Via through-holes	
	HGPM-...-E...-G8	Clamped	
	HGPM-...-E...-G9	With female thread and locating hole	

- 1) Valid for unthrottled operation
- 2) Spring resetting force between the jaws
- 3) End position drift under constant conditions of use with 100 consecutive strokes in the direction of movement of the gripper jaws
- 4) The indicated values are only valid when gripping with compressed air, not with spring force

Operating and environmental conditions			
Min. operating pressure	[bar]	4	
Max. operating pressure	[bar]	8	
Operating medium	Compressed air in accordance with ISO 8573-1:2010 [7:4:4]		
Note on operating/pilot medium	Operation with lubricated medium possible (in which case lubricated operation will always be required)		
Ambient temperature	[°C]	+5 ... +60	
Corrosion resistance class CRC ¹⁾	1		

- 1) Corrosion resistance class 1 according to Festo standard 940 070
Components requiring low corrosion resistance. Transport and storage protection. Parts that do not have primarily decorative surface requirements, e.g. in internal areas that are not visible or behind covers

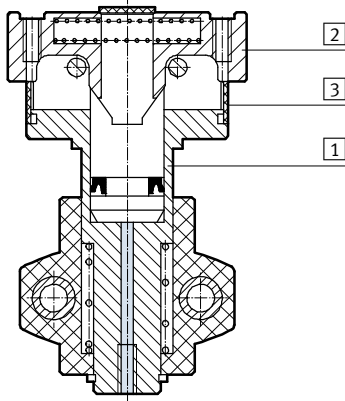
Weights [g]			
Size		8	12
With stroke compensation		19	62
With clamping spigot		11	41
With flange mounting		18	62

Parallel grippers HGPM, micro

Technical data

Materials

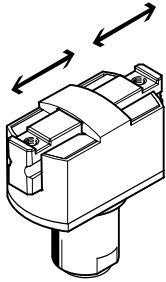
Sectional view



Parallel gripper

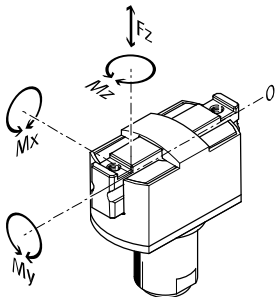
1	Body	Anodised aluminium
2	Gripper jaw	Stainless steel
3	Cover cap	Polyacetate
-	Note on materials	Copper and PTFE Conforms to RoHS

Gripping force [N] at 6 bar



Size	8		12	
	HGPM-...EO-...	HGPM-...EZ-...	HGPM-...EO-...	HGPM-...EZ-...
Gripping force per gripper jaw				
Opening	-	8	-	17.5
Closing	8	-	13.5	-
Total gripping force				
Opening	-	16	-	35
Closing	16	-	27	-

Characteristic load values per gripper jaw



The indicated permissible forces and torques apply to a single gripper jaw. The indicated values include the lever arm, additional applied loads caused

by the workpiece or external gripper fingers, as well as forces which occur during movement. The zero co-ordinate line (gripper jaw

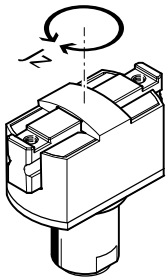
guide slot) must be taken into consideration for the calculation of torques.

Size		8	12
Max. permissible force F_z	[N]	10	30
Max. permissible torque M_x	[Nm]	0.15	0.5
Max. permissible torque M_y	[Nm]	0.15	0.5
Max. permissible torque M_z	[Nm]	0.15	0.5

Parallel grippers HGPM, micro

Technical data

Mass moment of inertia [kgm²x10⁻⁴]

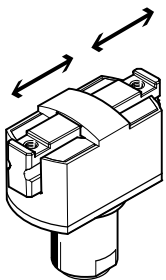


Mass moment of inertia [kgm²x10⁻⁴] for parallel grippers in relation to the central axis, without external gripper fingers, without load.

Size	8	12
With stroke compensation	0.00922	0.06674
With clamping spigot	0.00573	0.04252
With flange mounting	0.01712	0.07939

Opening and closing times [ms] at 6 bar

Without external gripper fingers



The indicated opening and closing times [ms] have been measured at room temperature and 6 bar operating pressure with vertically mounted gripper and without external gripper fingers. Load is increased if external gripper fingers are attached. This means that kinetic energy is also

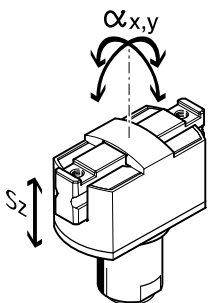
increased, as this is determined by gripper finger weight and velocity. If permissible kinetic energy is exceeded, various parts of the gripper may be damaged. This occurs when the applied load reaches the end-position and the cushioning is only

able to partially convert the kinetic energy into potential energy and heat energy. It thus becomes apparent that the indicated max. permissible applied load due to the external gripper fingers must be checked and maintained.

Size	8	12	
HGPM-...EO-...	Opening	4.9	11
	Closing	2.3	3.7
HGPM-...EZ-...	Opening	1.9	3
	Closing	4.1	8.3

Gripper jaw backlash

Without external gripper fingers



With parallel grippers, backlash occurs between the gripper jaws and the guide element due to the plain-bearing guide. The backlash values listed in the table have been

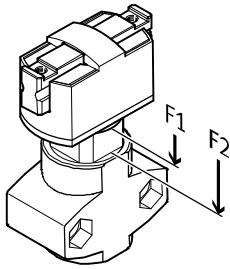
calculated based upon the traditional accumulative tolerance method and usually do not occur with mounted grippers.

Size	8	12
Gripper jaw backlash s_z	[mm]	< 0.03
Gripper jaw angular backlash α_x, α_y	[°]	< 0.5

Parallel grippers HGPM, micro

Technical data

Spring displacement forces [N]



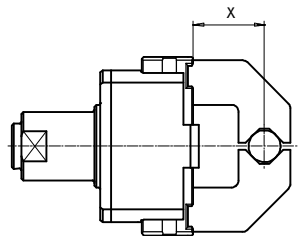
Theoretical actuating force due to stroke compensation for design variant with stroke compensation.

Size	8	12
Spring displacement forces F_1	4	10
Spring displacement forces F_2	6	23

Gripping force F_{Grip} per gripper jaw as a function of operating pressure and lever arm x

External and internal gripping (closing and opening)

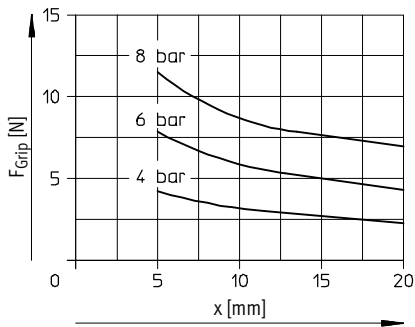
Gripping forces related to operating pressure and lever arm can be determined for the various sizes using the following graphs.



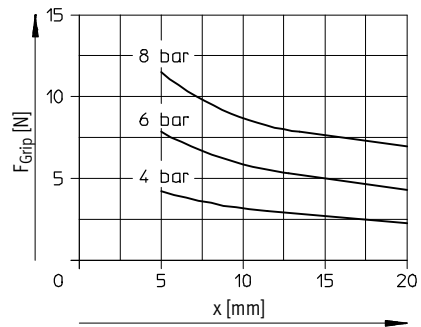
EO = External gripping (closing)

EZ = Internal gripping (opening)

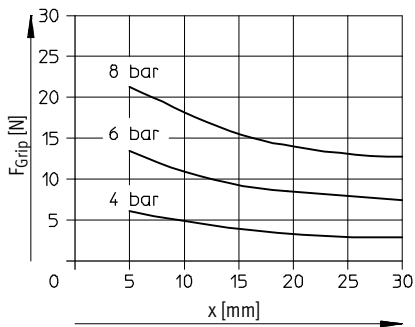
HGPM-08-EO-...



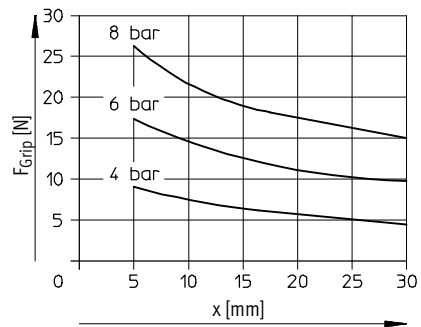
HGPM-08-EZ-...



HGPM-12-EO-...



HGPM-12-EZ-...

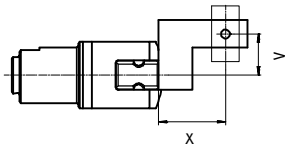


Parallel grippers HGPM, micro

Technical data

Gripping force F_{Grip} per gripper jaw at 6 bar as a function of lever arm x and eccentricity y

External and internal gripping (closing and opening)



Gripping forces at 6 bar dependent upon eccentric application of force

and the maximum permissible off-centre point of force application can

be determined for the various sizes using the following graphs.

Calculation example

Given:

HGPM-12-EZ-...

Lever arm $x = 10$ mm

Eccentricity $y = 11$ mm

To be found:

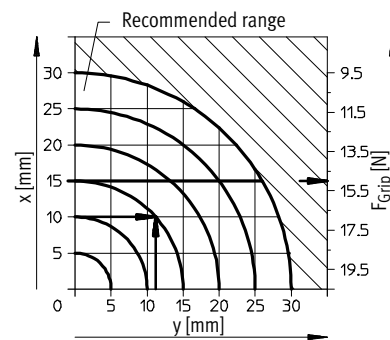
Gripping force at 6 bar

Procedure:

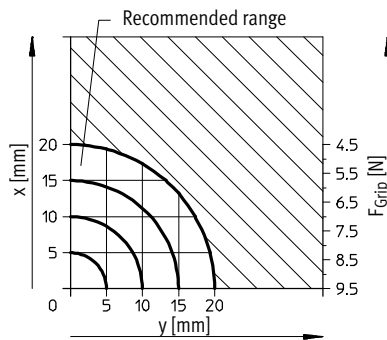
- Determine the intersection xy between lever arm x and eccentricity y in the graph for HGPM-12-EZ
- Draw an arc (with centre at origin) through intersection xy
- Determine the intersection between the arc and the X axis
- Read the gripping force

Result:

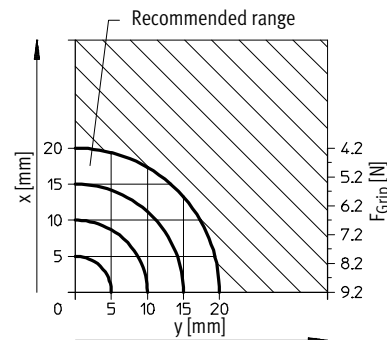
Gripping force = approx. 15 N



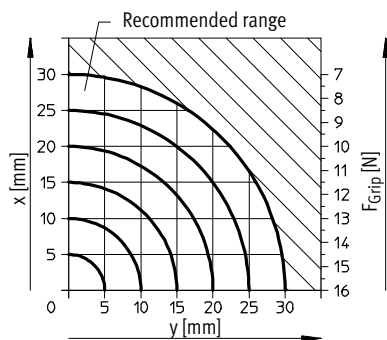
HGPM-08-EO-...



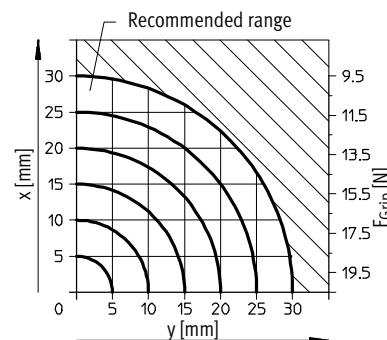
HGPM-08-EZ-...



HGPM-12-EO-...



HGPM-12-EZ-...



EO = External gripping (closing)

EZ = Internal gripping (opening)

Parallel grippers HGPM, micro

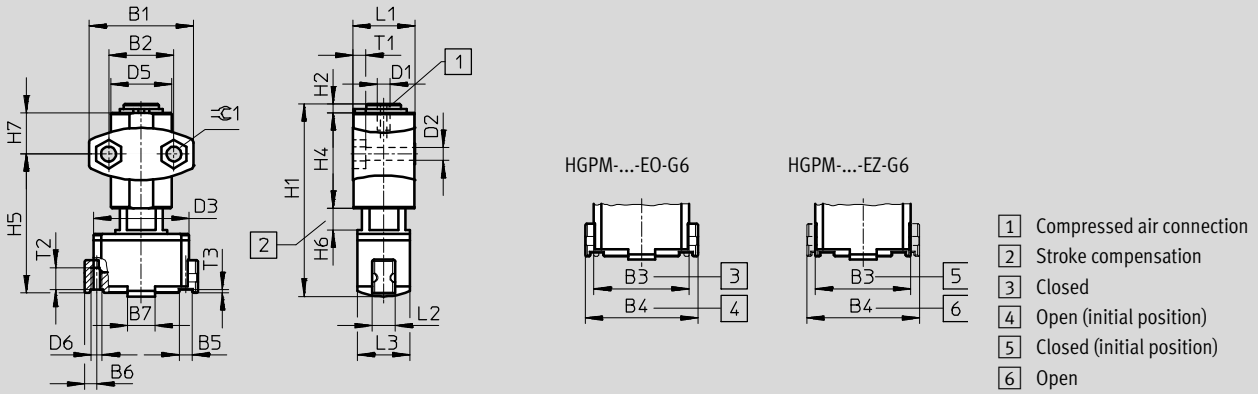
Technical data

FESTO

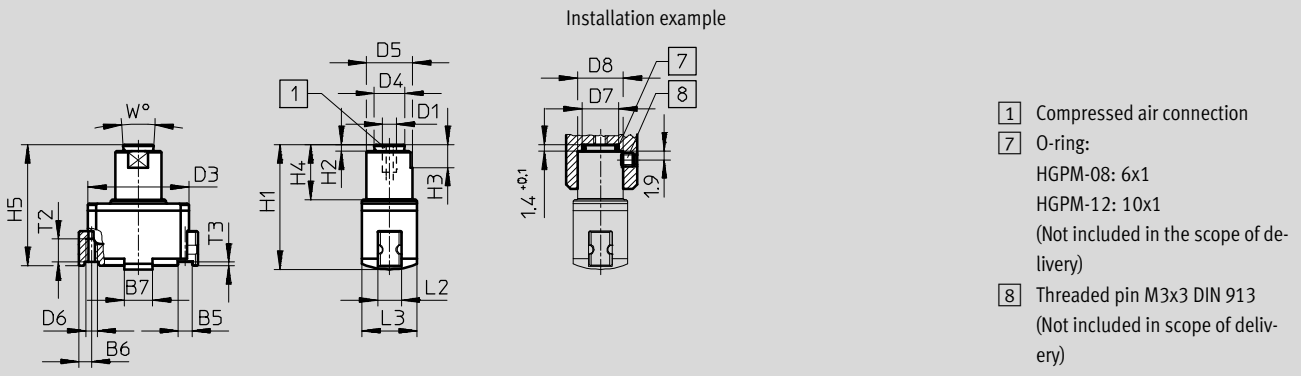
Dimensions

Download CAD data → www.festo.com

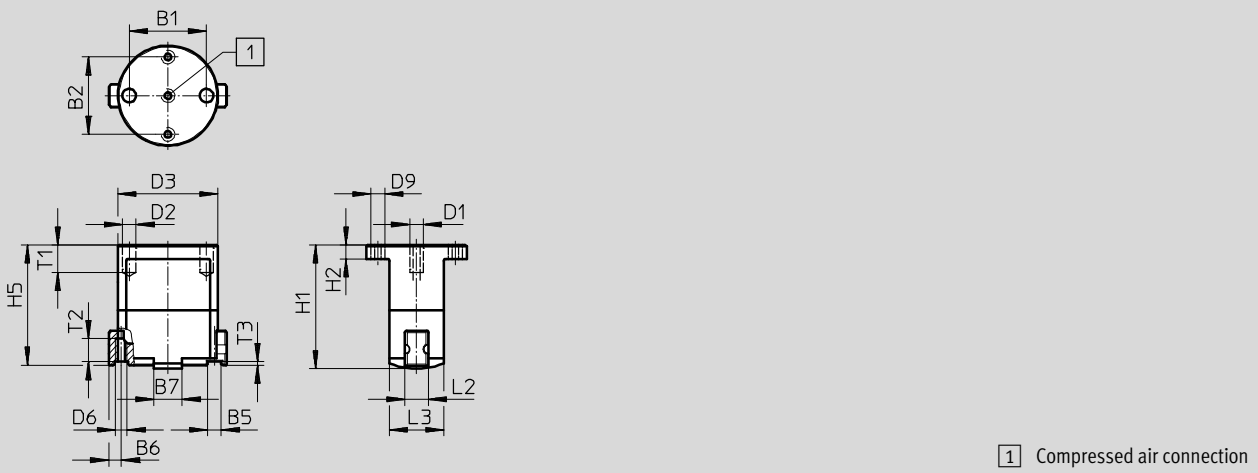
With stroke compensation – HGPM-...-E...-G6



With clamping spigot – HGPM-...-E...-G8



With flange mounting – HGPM-...-E...-G9



Parallel grippers HGPM, micro

Technical data

Type	B1	B2	B3 ±0.3	B4 ±0.3	B5 +0.05/+0.02	B6 +0.19/-0.23	B7 ±0.1	D1	D2 ∅	D3 ∅
HGPM-08-EO-G6	24 ±0.1	15 ±0.25	22	26	3	2.75	6.2	M3	3.4 +0.2	22
HGPM-08-EZ-G6										
HGPM-12-EO-G6	35 ±0.1	24 ±0.25	33	39	4	4	9	M3	4.5 +0.2	33
HGPM-12-EZ-G6										
HGPM-08-EO-G8	-	-	22	26	3	2.75	6.2	M3	-	22
HGPM-08-EZ-G8										
HGPM-12-EO-G8	-	-	33	39	4	4	9	M3	-	33
HGPM-12-EZ-G8										
HGPM-08-EO-G9	17 ±0.02	17 ±0.1	22	26	3	2.75	6.2	M3	3 F8	22
HGPM-08-EZ-G9										
HGPM-12-EO-G9	27 ±0.02	27 ±0.1	33	39	4	4	9	M3	3 F8	33
HGPM-12-EZ-G9										

Type	D4 ∅ ±0.1	D5 ∅	D6	D7 ∅ +0.1	D8 ∅ +0.1	D9	H1 ±0.3	H2	H3	H4	H5
HGPM-08-EO-G6	-	15 ±0.5	M2.5	-	-	-	44.2	2 +0.1/-0.3	-	22 -0.3	32.4 +0.8/-0.65
HGPM-08-EZ-G6											
HGPM-12-EO-G6	-	22 ±0.5	M3	-	-	-	63	3 +0.2/-0.3	-	29 -0.3	46.65 +0.9/-0.7
HGPM-12-EZ-G6											
HGPM-08-EO-G8	6.6	10 h8	M2.5	8	10	-	27.2	1.4 -0.1	5	12 ±0.1	26.9 +0.2/-0.25
HGPM-08-EZ-G8											
HGPM-12-EO-G8	10.6	15 h8	M3	12	15	-	41	1.4 -0.1	7 ±0.1	18 ±0.1	40.15 +0.2/-0.25
HGPM-12-EZ-G8											
HGPM-08-EO-G9	-	-	M2.5	-	-	M3	27.2	3 ±0.2	-	-	26.9 +0.2/-0.25
HGPM-08-EZ-G9											
HGPM-12-EO-G9	-	-	M3	-	-	M3	41	5 ±0.2	-	-	40.15 +0.2/-0.25
HGPM-12-EZ-G9											

Type	H6 +0.7/-0.2	H7 ±0.3	L1 +0.1/-0.3	L2 -0.1	L3 ±0.1	T1	T2 ¹⁾	T3	W	≲C1
HGPM-08-EO-G6	0 ... 5	9.5	14.3	5	12	3 -0.2	4	0.8	-	5.7
HGPM-08-EZ-G6										
HGPM-12-EO-G6	0 ... 8	12.5	20.35	7	18	4 -0.2	6	1	-	7.5
HGPM-12-EZ-G6										
HGPM-08-EO-G8	-	-	-	5	12	-	4	0.8	8°	-
HGPM-08-EZ-G8										
HGPM-12-EO-G8	-	-	-	7	18	-	6	1	8°	-
HGPM-12-EZ-G8										
HGPM-08-EO-G9	-	-	-	5	12	min. 6	4	0.8	-	-
HGPM-08-EZ-G9										
HGPM-12-EO-G9	-	-	-	7	18	min. 6	6	1	-	-
HGPM-12-EZ-G9										

1) Do not exceed max. thread screw-in depth

Ordering data							
Single-acting	Size [mm]	Mounting options					
		With stroke compensation Part No. Type		With clamping spigot Part No. Type		With flange mounting Part No. Type	
Gripper jaws open	8	197559	HGPM-08-EO-G6	197560	HGPM-08-EO-G8	197561	HGPM-08-EO-G9
	12	197565	HGPM-12-EO-G6	197566	HGPM-12-EO-G8	197567	HGPM-12-EO-G9
Gripper jaws closed	8	197562	HGPM-08-EZ-G6	197563	HGPM-08-EZ-G8	197564	HGPM-08-EZ-G9
	12	197568	HGPM-12-EZ-G6	197569	HGPM-12-EZ-G8	197570	HGPM-12-EZ-G9

Festo - Your Partner in Automation



1 Festo Inc.
5300 Explorer Drive
Mississauga, ON L4W 5G4
Canada

Festo Customer Interaction Center
Tel: 1 877 463 3786
Fax: 1 877 393 3786
Email: customer.service.ca@festo.com

2 Festo Pneumatic
Av. Ceylán 3,
Col. Tequesquináhuac
54020 Tlalnepantla,
Estado de México

Multinational Contact Center
01 800 337 8669
ventas.mexico@festo.com

3 Festo Corporation
1377 Motor Parkway
Suite 310
Islandia, NY 11749

Festo Customer Interaction Center
1 800 993 3786
1 800 963 3786
customer.service.us@festo.com

4 Regional Service Center
7777 Columbia Road
Mason, OH 45040

Connect with us



www.festo.com/socialmedia



www.festo.com

Subject to change