RE 29 041/11.02

Servo solenoid valves with on-board electronics (OBE) Type 4WRREH 6

Size 6
Series 1X
Maximum working pressure 315 bar
Maximum flow rate 40 l/min (Δp 70 bar)



Type 4WRREH 6 ..B..-1X/G24...

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Features

- Directly operated High Response servo solenoid valve NG 6, with control piston and sleeve in servo quality
- Double-stroke solenoid with integral position feedback and on-board electronics (OBE), calibrated at the factory
- Prepared as a pilot valve, e.g. for 3/2 control cartridge with position transducer, position-controlled
- -~ Electrical connection 11P+PE Signal input difference amplifier with interface B5 $\pm 10\,\mathrm{V}$
- Suitable for electrohydraulic controllers in production and testing systems
- For subplate attachment, mounting hole configuration to DIN 24 340 Form A, ISO 4401 and CETOP-RP 121 H
- Subplates as per catalogue section RE 45 053 (order separately)
- Line sockets to DIN 43 563-AM6, see catalogue section RE 08 008 (order separately)

Variants on request

- For standard applications
- Special symbols for extending the module.



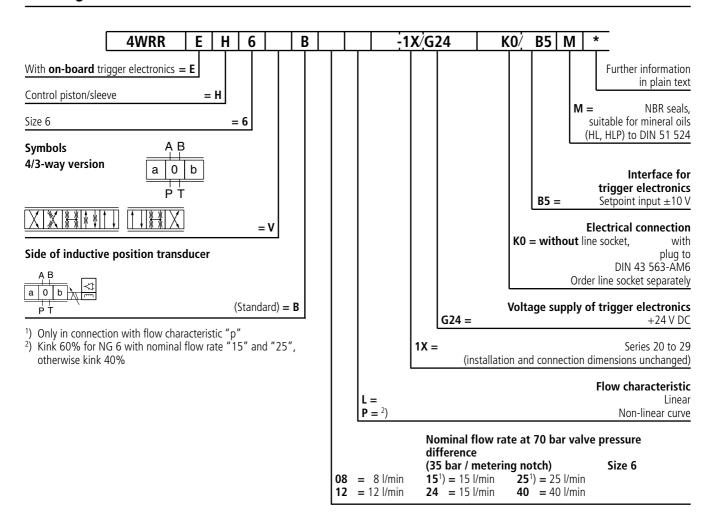
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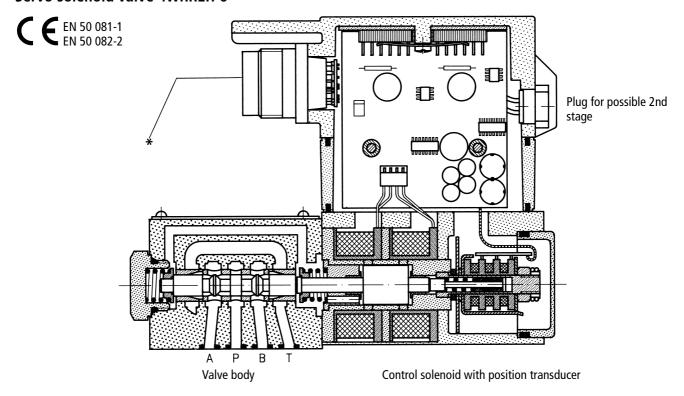
4WRREH 6 **1**/10 RE 29 041/11.02



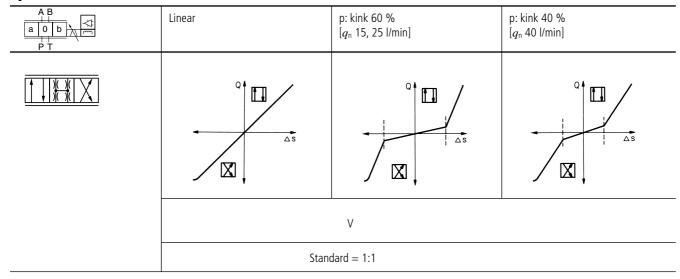
Preferred types (available at short notice)

Material no.	Type 4WRREH 6
0 811 404 723	4WRREH 6 VB08L –1X/G24K0 / B5M
0 811 404 722	4WRREH 6 VB12L –1X/G24K0 / B5M
0 811 404 721	4WRREH 6 VB24L –1X/G24K0 / B5M
0 811 404 720	4WRREH 6 VB40L –1X/G24K0 / B5M
0 811 404 725	4WRREH 6 VB15P –1X/G24K0 / B5M
0 811 404 726	4WRREH 6 VB25P –1X/G24K0 / B5M
0 811 404 727	4WRREH 6 VB40P –1X/G24K0 / B5M

Servo solenoid valve 4WRREH 6



Symbols



Accessories, not included in scope of delivery

(4 x) ₪ M 5 x 30 DIN 912–10.9	Fastening screws	2 910 151 166	
*	Line sockets 11P+PE	KS	1 834 482 142

Testing and service equipment

- Test box type VT-PE-TB3, see RE 30 065
- Test adapter 11P+PE type VT-PA-1, see RE 30 067

General							
Construction	Spool type	Spool type valve, operated directly, with steel sleeve					
Actuation	Proportiona	Proportional double-stroke solenoid with position control, OBE					
Type of mounting	Subplate, m	Subplate, mounting hole configuration NG 6 (ISO 4401 and CETOP-RP 121 H)					
Installation position	Optional	Optional					
Ambient temperature range	− 20 +5	−20 +50 °C					
Weight	2.5 kg	2.5 kg					
Vibration resistance, test condition	Max. 25 g,	shaken in 3 di	mensions (24 h	1)			
Hydraulic (measured with HLP 46, $\vartheta_{\text{oil}} = 40$	°C ±5 °C)						
Pressure fluid	Hydraulic o	il to DIN 51 5	24 535, oth	er fluids after p	rior consultatio	n	
Viscosity range, recommended max. permitted		20 100 mm²/s 10 800 mm²/s					
Pressure fluid temperature range	-20 +6	−20 +65 °C					
Purity class to ISO code		Maximum permitted degree of contamination of pressure fluid to ISO 4406 (C) Class 18/16/13 ¹)					
Flow direction	See symbol						
Nominal flow [l/min] at $\Delta p = 35$ bar per notch*	8	12	15	24	25	40	
Max. working pressure	Port P, A, B	Port P, A, B: 315 bar					
Max. pressure	Port T: 100	bar					
Operating limits at Δp [bar]	315	315	315	315	315	250	
Leakage [cm³/min] at 100 bar	< 250	< 300	_	< 500	_	< 900	
+	_	_	< 180	_	< 250	_	
Static/Dynamic	'	'	'	'	'		
Hysteresis	≦ 0.2 %						
Manufacturing tolerance for $q_{\text{max.}}$	<10 %	<10 %					
Response time for signal change 0 100 %	≤ 5 ms	≦ 5 ms					
Thermal drift	Zero point	Zero point displacement $<$ 1 % at ΔT = 40 °C					
Zero adjustment	Factory-set	Factory-set ±1 %					
Conformity	C EN EN	C € EN 50 081-1 EN 50 082-2					

¹⁾ The purity classes stated for the components must be complied with in hydraulic systems. Effective filtration prevents problems and also extends the service life of components. For a selection of filters, see catalogue sections RE 50 070, RE 50 076 and RE 50 081.

$$q_{\rm x} = q_{\rm nom.} \cdot \sqrt{\frac{\Delta p_{\rm x}}{35}}$$

^{*} Flow rate at a different Δp

Technical data (For device applications beyond the stated values, please consult us!)

Electrical, trigger electronics integrated in the valve

Cyclic duration factor		100 %, max. current input 30 VA (24 V DC)			
Degree of protection		IP 65 to DIN 40 050 and IEC 14 434/5			
Connection		Plug, 11P+PE	Data		
Power supply	1)	1	+24 V DC _{nom.} , fuse 2.5 A _F (output stages)		
24 V DC _{nom.}		2	0 V power ground		
	2)	9	+24V DC _{nom.} signal part		
		10	0 V signal ground		
Input signal	3)	4	$\left(\frac{U_{\text{IN}}}{U_{\text{IN}}}\right)$ Difference amplifier, $R_{\text{i}} = 100 \text{ k}\Omega$		
±10 V		5	$\left[egin{array}{c} rac{U_{\text{IN}}}{U_{\text{IN}}} \end{array} ight]$ Difference amplifier, $R_{\text{i}}=100~\text{k}\Omega$		
Feedback signal (LVDT)		6	$\pm 10 \text{ V DC}$, $R_a = 1 \text{ k}\Omega$		
		7	0 V, reference point		
Enabling input		3	> 8,5 V to 24 V DC _{nom.} (max. 40 V DC)		
			$R_{\rm i} = 10 \ {\rm k}\Omega$		
Signals	4)	8	Enabling acknowledgement +24 V DC		
		11	Fault signal: no fault +24 V DC		
Protective conductor		\bigcirc	Only connect when transformer of 24 V DC system does		
		(not conform to standard VDE 0551		
Connecting cable		Recommended Ø 12 14 mm: screened			
		max. 20 m 0.75 mm ²			
		max. 40 m 1.0 mm ²			

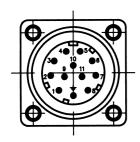
 $\begin{array}{cccc} 24 \ V \ DC_{nom.} & -min. \ \ 21 \ V \ DC \\ -max. \ \ 40 \ V \ DC \end{array}$

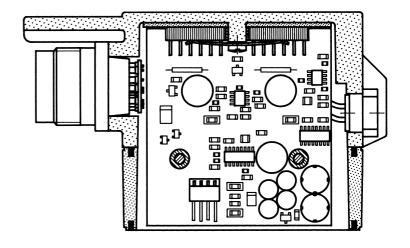
- U_B (Pin 1) = output stage supply

 Valve "OFF" < 13.4 V DC
 Valve "ON" > 16.8 V DC

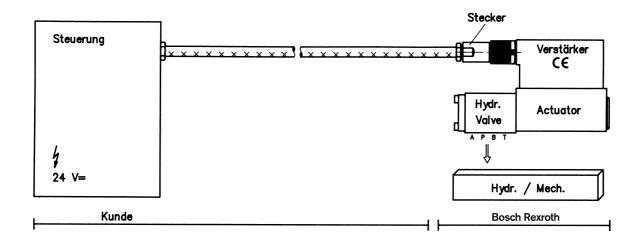
 No fault signal (Pin 11)
- $^2)$ U_S (Pin 9) = signal electronics supply Valve "OFF" < 16.8 V DC Fault signal (Pin 11) Valve "ON" $\,>$ 19.5 V DC No fault signal (Pin 11)
- ³) Inputs: dielectric strength to withstand up to max. 50 V.
- ⁴) Signals can bear a load of max. 20 mA and are resistant to shorts to ground.

11P+PE





For electrical data, see page 5 and Operating Instructions 1 819 929 083



Technical notes on the cable

Version:

- Multi-wire cable
- Extra-finely stranded wire to VDE 0295, Class 6
- Protective conductor, green/yellow
- Cu braided screen

Types:

– e.g. Ölflex-FD 855 <u>C</u>P

(from Lappkabel company)

No. of wires: – Determined by type of valve, plug types and signal assignment

Cable Ø: $-0.75 \text{ mm}^2 \text{ up to } 20 \text{ m length}$

 $-1.0 \text{ mm}^2 \text{ up to } 40 \text{ m length}$

Outside Ø: -9.4 ... 11.8 mm - Pg 11

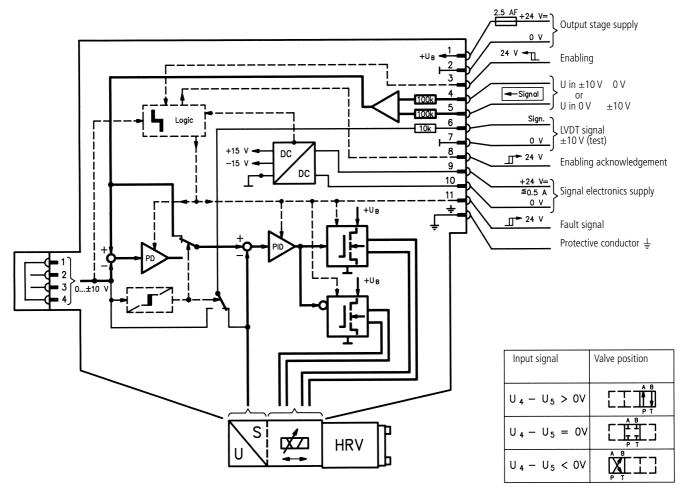
- 12.7 ... 13.5 mm - Pg 16

Note

Electrical signals emitted via the trigger electronics (e.g. actual values) must not be used to shut down safety-relevant machine functions! (See European Standard, "Technical Safety Requirements for Fluid-Powered Systems and Components — Hydraulics", EN 982.)

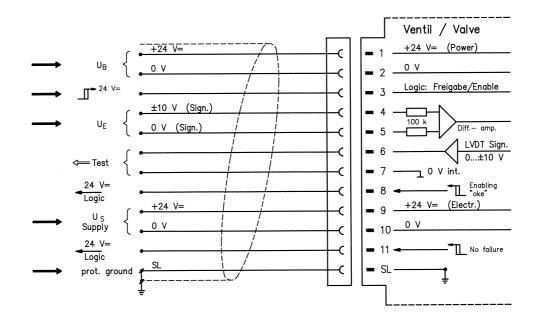
Block diagram / pin assignment

Version B5: $U_E \pm 10 \text{ V}$



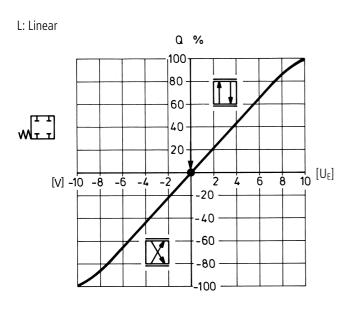
Pin assignment 11P + PE

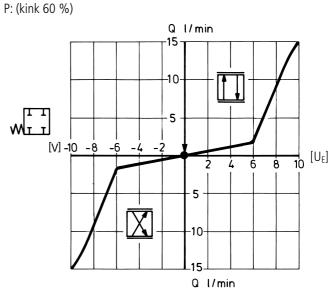
Version B5: $U_E \pm 10 \text{ V}$ ($R_i = 100 \text{ k}\Omega$)

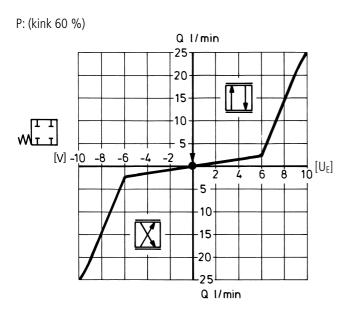


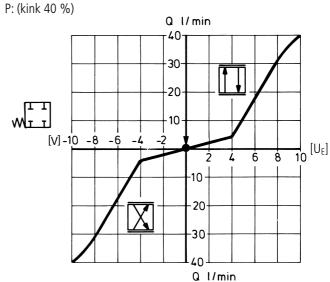
Flow rate/Signal function

 $Q = f(U_E)$









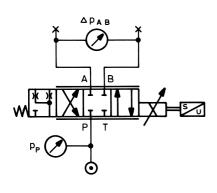
Note

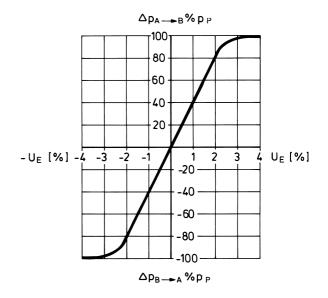
Highly dynamic servo solenoid valves do not have a safe basic position when they are switched off. For this reason, many applications require the use of "additional check valves", which must be taken into account during the On/Off switching sequence.

When switched off, the spool tends to rest in the P-B/A-T position.

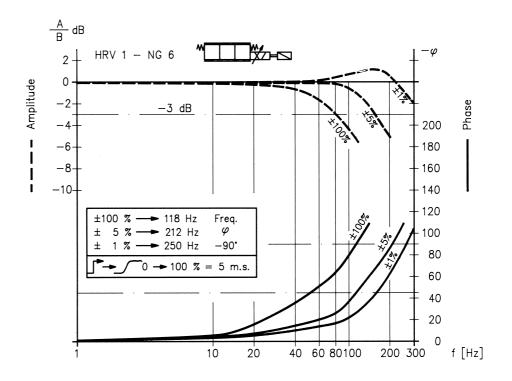
This cannot be guaranteed if dirt is present.

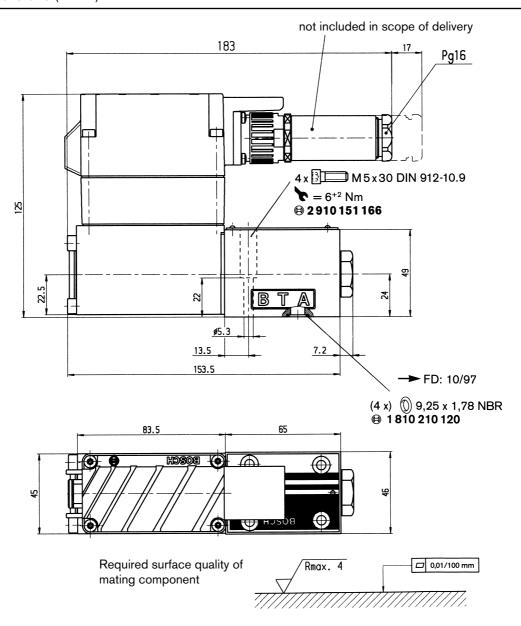
Pressure gain





Bode diagram

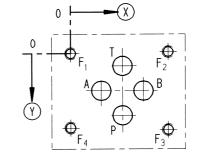




Mounting hole configuration: NG 6 (DIN 24 340 Form A,

ISO 4401 and CETOP-RP 121 H)

For subplates, see catalogue section RE 45 053



- 1) Deviates from standard
- ²) Thread depth: Ferrous metal 1.5 x Ø*

Non-ferrous 2 x Ø * (NG 10 min. 10.5 mm)

	P	A	T	В	F ₁	F ₂	F ₃	F ₄
\otimes	21.5	12.5	21.5	30.2	0	40.5	40.5	0
\bigcirc	25.9	15.5	5.1	15.5	0	-0.75	31.75	31
Ø	81)	81)	81)	81)	M5 ²⁾	M5 ²⁾	M5 ²⁾	M5 ²⁾

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