Industrial **Electric Drives** Hydraulics and Controls

RE 29 077/01.03

List of contents

Servo solenoid valves with on-board electronics (OBE) Type 4WRVE 10...25

Linear Motion and

Assembly Technologies

Size 10, 16, 25 Series 2X Maximum working pressure 350 bar Maximum flow rate 430 l/min (Δp 10 bar)

- Pilot operated High Response servo solenoid valves NG 10 to NG 25, with control piston and sleeve in servo quality On-board electronics (OBE) with position controller for the pilot and main stages, calibrated at the factory Flow characteristic • P = Non-linear curve • L = Linear (only available on request) Electrical connection 11P+PE

Suitable for electrohydraulic controllers in production and testing systems

For subplate attachment, mounting hole configuration to DIN 24 340 Form A, ISO 4401 and CETOP-RP 121 H

Subplates as per catalogue section, NG 10 RE 45 055, NG 16 RE 45 057 and NG 25 RE 45 059

 Line sockets to DIN 43 563-AM6, see catalogue section RE 08 008 (order separately

Variants on request

- For standard applications
- Special symbols for plastic injection-moulding machines and for extending the module.

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by Bosch Rexroth AG, Industrial Hydraulics, D-97813 Lohr am Main

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This work has been compiled with the greatest care, and all the information therein has been checked to ensure correctness. We must reserve the right to make changes on the grounds of continual product development. No liability can be accepted for incomplete or inaccurate information.

Features

Service

Automation

Pneumatics

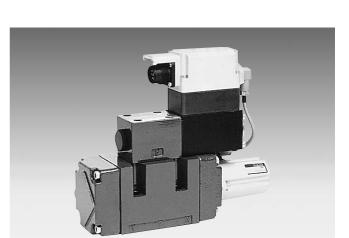
Mobile

Hydraulics

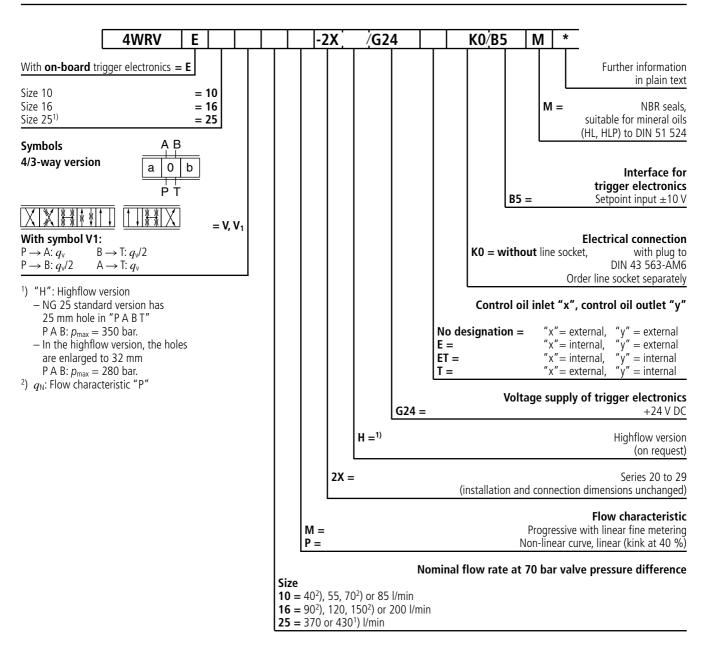
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On-board trigger electronics	8
Performance curves	9 and 10
Device dimensions	11 to 13
Mounting hole configurations	14 and 15

Type 4WRVE-2X/G24...

- Main stage in servo quality with position feedback
 - M = Progressive with fine metering notch
- Signal input difference amplifier with interface B5 ± 10 V



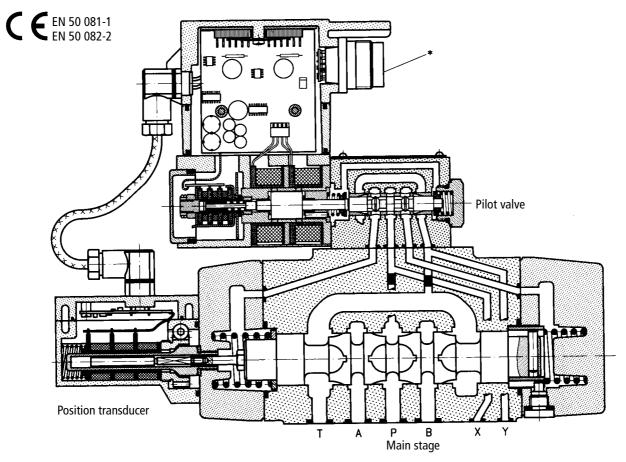




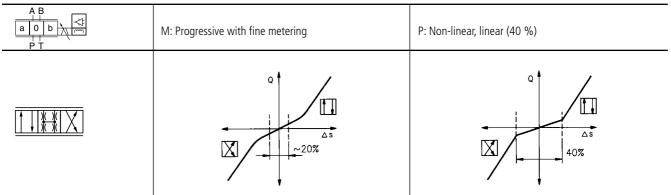
Preferred types (available at short notice)

Material no.	Type 4WRVE	Material no.	Type 4WRVE				
NG 10	V/V1	NG 16	V/V1				
0 811 404 690	4WRVE 10 V – 55M 2X/G24 K0 / B5M	0 811 404 290	4WRVE 16 V – 120M 2X/G24 K0 / B5M				
0 811 404 699	4WRVE 10 V1 – 55M 2X/G24 K0 / B5M	0 811 404 294	4WRVE 16 V1 – 120M 2X/G24 K0 / B5M				
0 811 404 691	4WRVE 10 V - 85M 2X/G24 K0 / B5M	0 811 404 291	4WRVE 16 V - 200M 2X/G24 K0 / B5M				
0 811 404 697	4WRVE 10 V1 – 85M 2X/G24 K0 / B5M	0 811 404 295	4WRVE 16 V1 – 200M 2X/G24 K0 / B5M				
0 811 404 693	4WRVE 10 V - 40P 2X/G24 K0 / B5M	0 811 404 296	4WRVE 16 V – 90P 2X/G24 K0 / B5M				
0 811 404 695	4WRVE 10 V1 – 40P 2X/G24 K0 / B5M	0 811 404 298	4WRVE 16 V1 – 90P 2X/G24 K0 / B5M				
0 811 404 694	4WRVE 10 V - 70P 2X/G24 K0 / B5M	0 811 404 297	4WRVE 16 V - 150P 2X/G24 K0 / B5M				
0 811 404 696	4WRVE 10 V1 – 70P 2X/G24 K0 / B5M	0 811 404 299	4WRVE 16 V1 – 150P 2X/G24 K0 / B5M				
		NG 25	V/V1				
		0 811 404 445	4WRVE 25 V - 370M 2X/G24 K0 / B5M				
		0 811 404 447	4WRVE 25 V1 – 370M 2X/G24 K0 / B5M				

Servo solenoid valve 4WRVE 10 ... 25



Symbols



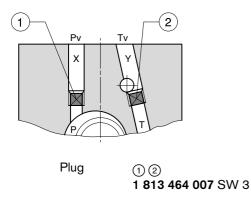
Accessories, not included in scope of delivery

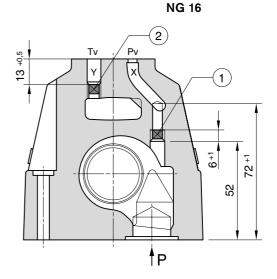
Fastening screws		NG 10	4 x M 6 x 40, DIN 912-10.9		2 910 151 209
B T T T		NG 16	2 x M 6 x 45, DIN 912-10.9		2 910 151 211
E≦_L₽			4 x M 10 x 50, DIN 912-10.9		2 910 151 301
		NG 25	6 x M 12 x 60, DIN 912-10.9		2 910 151 354
*		Line soc	ket 11P+PE	KS	1 834 484 142
	Pg 16				

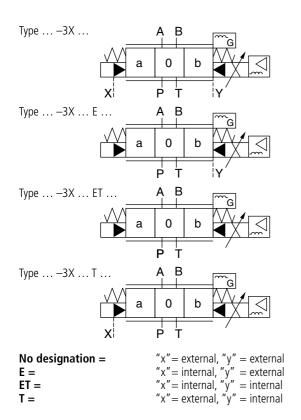
Testing and service equipment

- Test box type VT-PE-TB3, see RE 30 065
 Test adapter 11P+PE type VT-PA-1, see RE 30 067

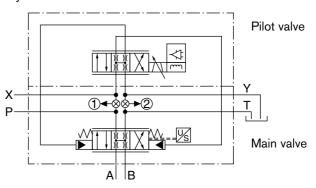
NG 10, 25







Symbol in detail



Conversion

The pilot valve can be supplied with oil both via ports X and Y (external) and from the main flow ducts P and T.

In the basic version, the valve is equipped with the plugs ① and ②, i.e. X and Y are external.

For valve versions with X and/or Y as internal, see ordering overview or carry out the conversion (see diagram above). When the control oil supply or discharge is changed, the part number must also be changed.

Important

Servo solenoid valves (pilot operated) do not have a closed middle position when switched off! They only perform their function in an active, closed control loop, even when the pilot valve features a relief (fail-safe) 4th symbol. For details on "switch-off behaviour", see Technical data.

Technical data (For device applications beyond the stated values, please consult us!)

General											
Construction		Spool type va	alve, pilot opera	ted							
Actuation		4WREH servo solenoid valve NG 6 – OBE, with position controller for pilot valve and main sta									
Type of mounting		Subplate, mo	Subplate, mounting hole configuration NG 10 25 (ISO 4401 and CETOP-RP 121 H)								
Installation position		Optional									
Ambient temperature range		-20 +50	°C								
Weight		NG 10 8.0 k	g	NG 16 10.4 kg	NG 25 18.2 kg						
Vibration resistance, test con	ndition	Max. 25 g, sł	naken in 3 dime	ensions (24 h)							
Hydraulic (measured with	HLP 46, $\vartheta_{oil} = 40$ °	°C ±5 °C)									
Pressure fluid		Hydraulic oil	to DIN 51 524	535, other fluids after	prior consultation						
Viscosity range, recommend max. permit		20 100 m 10 800 m									
Pressure fluid temperature r	ange	-20 +65	°C								
Purity class to ISO code			rmitted degree (C) Class 18/16	of contamination of press /13 ¹)	sure fluid						
Flow direction		See symbol									
Nominal flow [l/min] at		N	G 10	NG 16	NG 25						
$\Delta p = 5$ bar per notch*		40 55	70 85	90 120 150 2	00 370						
Max. working pressure		Port P, A, B: 350 bar									
Max. pressure		Port T, X, Y: 250 bar									
q _{max.} [l/min]		1	70	900							
$q_{\rm N}$ pilot valve [l/min]			8	24	40						
Leakage [cm ³ /min] of pilot v at 100 bar	valve	<	180	<300	<500						
Leakage [cm ³ /min] of main stage at 100 bar	++	<400	<600	<1,000	<1,000						
Control oil pressure "pilot s	tage"	min. 10 bar									
		max. 250 bar									
Static/Dynamic											
Hysteresis		< 0.1 %, scarcely measurable									
Manufacturing tolerance for	^r q _{max.}	≦10%									
Response time for signal	0 100 %		12	15	23						
change (at X = 100 bar)	0 10 %		6	7	10						
Response time for signal	0 100 %		40	50	90						
change (at X = 10 bar)	0 10%		20	20	30						
Switch-off behaviour				lot valve undefined in P-B d 100 % (PB/AT or PA/BT							
Thermal drift		Zero point di	splacement <	% at Δ <i>T</i> = 40 °C							
Zero adjustment		Factory-set ±	1%								
Conformity) 081-1) 082-2								

 The purity classes stated for the components must be complied with in hydraulic systems. Effective filtration prevents problems and also extends the service life of components. For a selection of filters, see catalogue sections RE 50 070, RE 50 076 and RE 50 081.

* Flow rate at a different Δp

 $q_{\rm x} = q_{\rm nom.} \cdot \sqrt{\frac{\Delta p_{\rm x}}{5}}$

Important

Pilot operated 4WRLE servo solenoid valves only perform their function in an active closed control loop and do not have a safe basic position when switched off. For this reason, many applications require the use of "additional check valves", which must be taken into account during the On/Off switching sequence.

Cyclic duration factor		100 %, max. cur	100 %, max. current input 30 VA (24 V DC)					
Degree of protection		IP 65 to DIN 40	P 65 to DIN 40 050 and IEC 14 434/5					
Connection		Plug, 11P+PE	Data					
Power supply 24 V DC _{nom.}	1)	1 2	+24 V DC _{nom.} , fuse 2.5 A _F (output stages) 0 V power ground					
	2)	9 10	+24 V DC _{nom.} signal part 0 V signal ground					
Input signal ±10 V	3)	4 5	$\left \frac{U_{IN}}{U_{IN}} \right $ Difference amplifier, $R_i = 100 \text{ k}\Omega$					
Feedback signal (LVDT)		6 7	$\pm 10 \text{ V DC}, R_a = 1 \text{ k}\Omega$ 0 V, reference point					
Enabling input		3	> 8.5 V to 24 V DC _{nom.} (max. 40 V DC) $R_{\rm i} = 10 \ \rm k\Omega$					
Signals	4)	8	Enabling acknowledgement +24 V DC Fault signal: no fault +24 V DC					
Protective conductor		(L)	Only connect when transformer of 24 V DC system does not conform to standard VDE 0551					
Connecting cable		Recommended Ø 12 14 mm: screened max. 20 m 0.75 mm ² max. 40 m 1.0 mm ²						

 $24 \text{ V DC}_{nom.}$ – min. 21 V DC- max. 40 V DC

¹) U_B (Pin 1) = output stage supply - Valve "OFF" < 13.4 V DC - Valve "ON" > 16.8 V DC

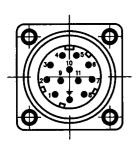
No fault signal (Pin 11)

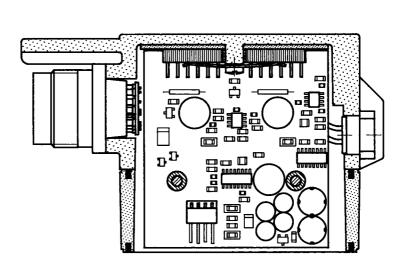
²) U_S (Pin 9) = signal electronics supply - Valve "OFF" < 16.8 V DC Fault signal (Pin 11) - Valve "ON" > 19.5 V DC No fault signal (Pin 11)

³) Inputs: dielectric strength to withstand up to max. 50 V.

⁴) Signals can bear a load of max. 20 mA and are resistant to shorts to ground.

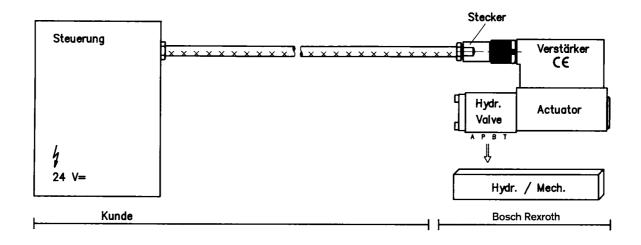
11P+PE





Connection

For electrical data, see page 6 and Operating Instructions 1 819 929 083



Technical notes on the cable

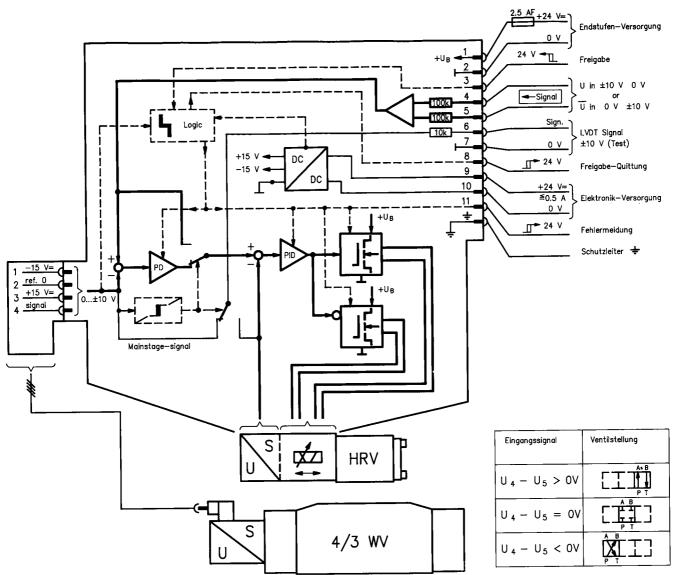
Version:	 Multi-wire cable Extra-finely stranded wire to VDE 0295, Class 6 Protective conductor, green/yellow
Types:	 Cu braided screen e.g. Ölflex-FD 855 <u>CP</u> (from Lapakabel sompany)
No. of wires:	(from Lappkabel company) – Determined by type of valve, plug types and signal assignment
Cable Ø:	-0.75 mm^2 up to 20 m length
	-1.0 mm^2 up to 40 m length
Outside Ø:	– 9.4 11.8 mm – Pg 11 – 12.7 13.5 mm – Pg 16
	1217 11 1313 1111 1910

Important

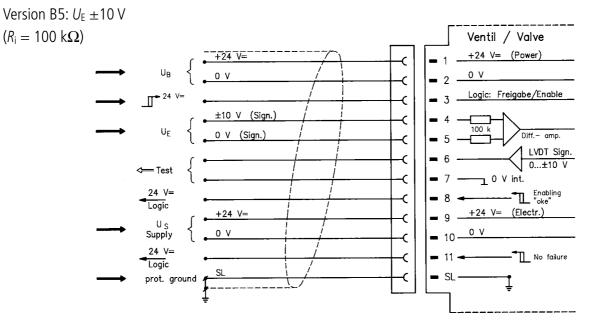
Electrical signals emitted via the trigger electronics (e.g. actual values) must not be used to shut down safety-relevant machine functions! (See European Standard, "Technical Safety Requirements for Fluid-Powered Systems and Components – Hydraulics", EN 982.)

Block diagram / pin assignment

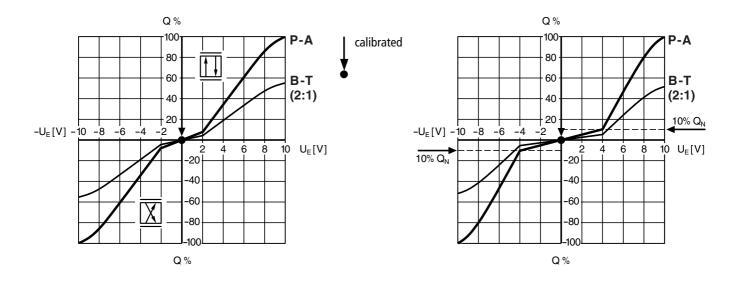
Version B5: $U_{\rm E} \pm 10$ V



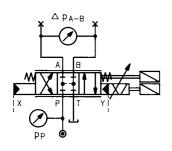
Pin assignment 11P + PE

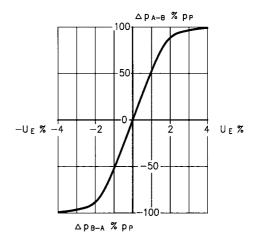


Flow rate/Signal function $Q = f(U_E)$

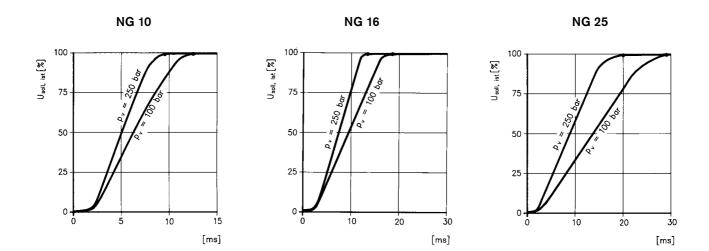


Pressure gain $\Delta = f(U_E)$

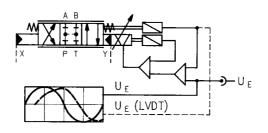






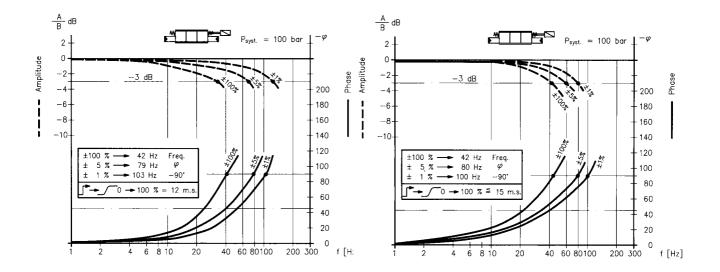


Bode diagrams

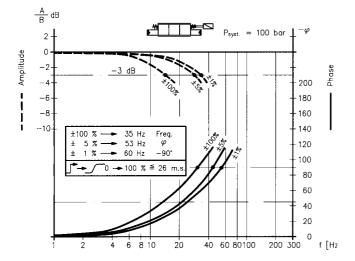


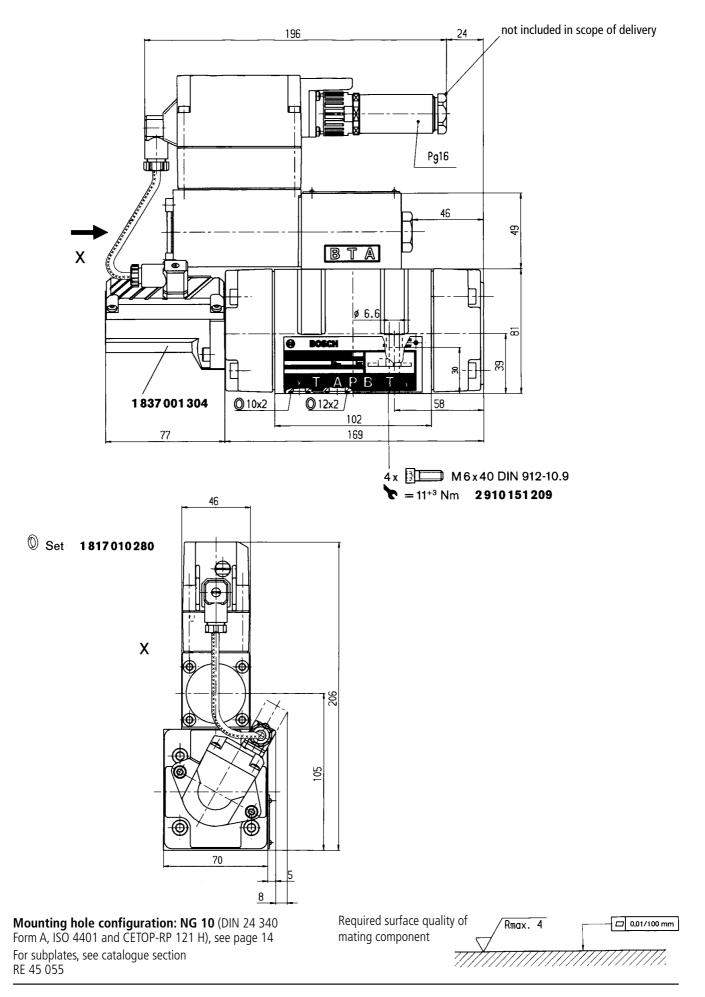
NG 10

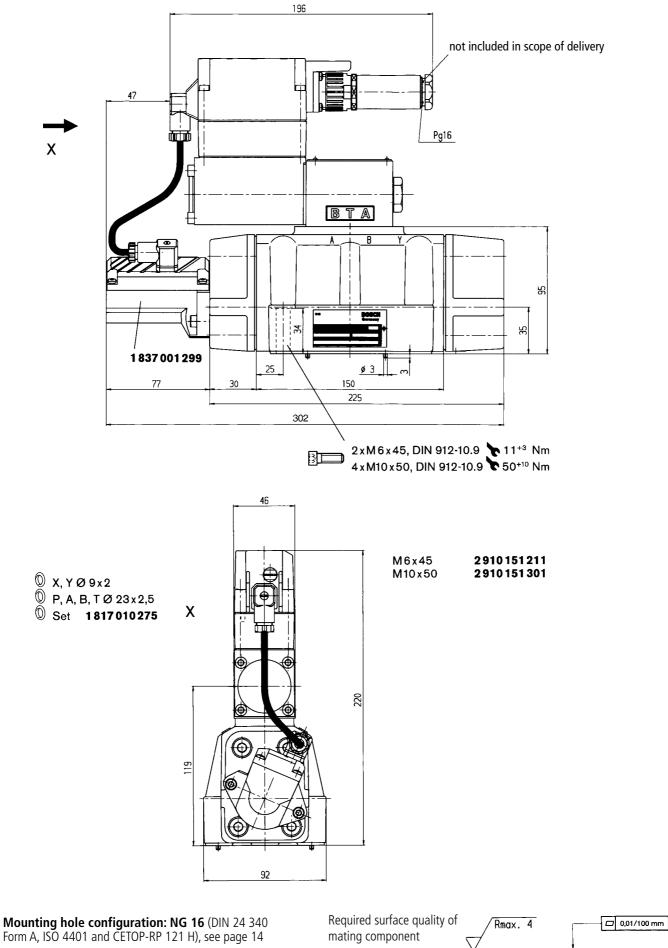
NG 16



NG 25

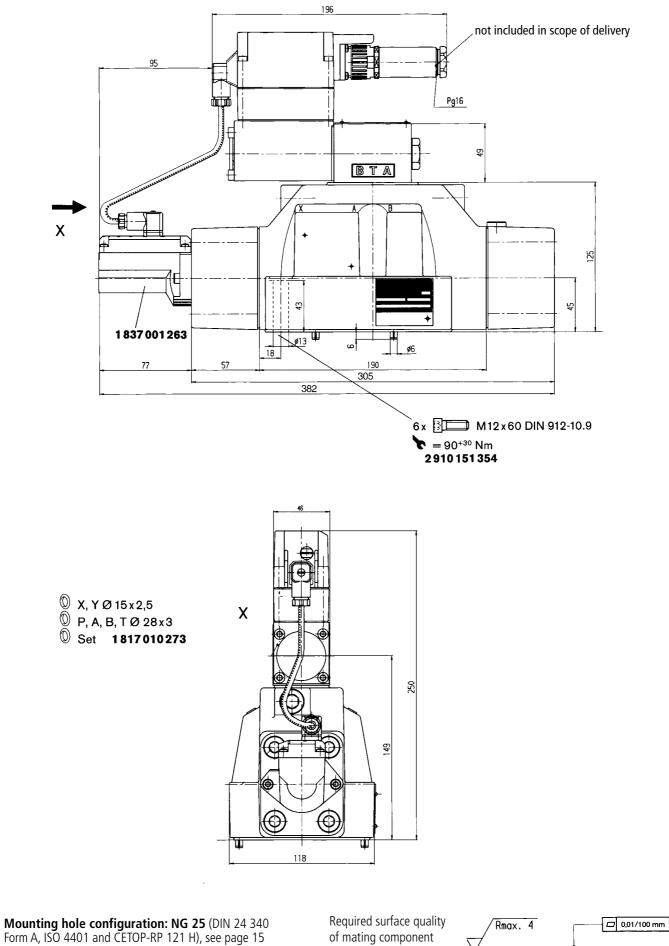






For subplates, see catalogue section RE 45 057

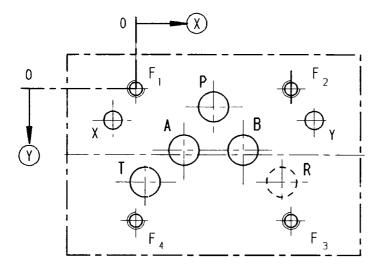
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Form A, ISO 4401 and CETOP-RP 121 H For subplates, see catalogue section RE 45 059

7)

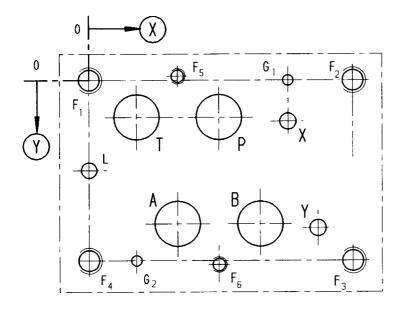
NG 10 - ISO 4401



¹⁾ Deviates from standard ²⁾ Thread depth: Ferrous metal 1.5 x \emptyset * Non-ferrous 2 x \emptyset * (NG 10 min. 10.5 mm)

	Р	A	T	В	F ₁	F ₂	F ₃	F ₄	Х	Y	R
\otimes	27	16.7	3.2	37.3	0	54	54	0	-8	62	50.8
\heartsuit	6.3	21.4	32.5	21.4	0	0	46	46	11	11	32.5
Ø	10.5 ¹⁾	10.5 ¹⁾	10.5 ¹⁾	10.5 ¹⁾	M 6 ²⁾	M 6 ²⁾	M 6 ²⁾	M 6 ²⁾	6.3	6.3	10.5 ¹⁾

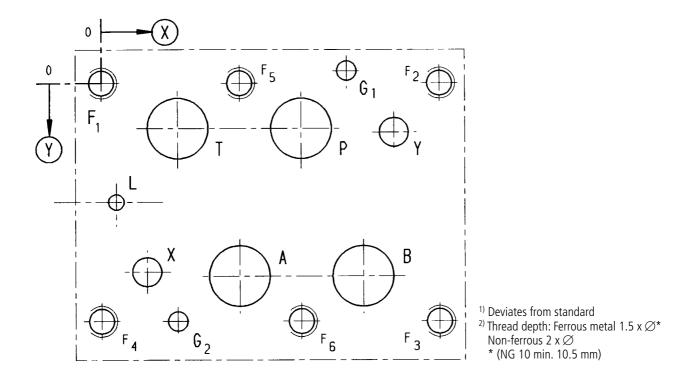
NG 16 - ISO 4401



¹⁾ Deviates from standard ²⁾ Thread depth: Ferrous metal 1.5 x \emptyset * Non-ferrous 2 x \emptyset * (NG 10 min. 10.5 mm)

	P	A	T	В	L	X	Y	G ₁	G ₂	F ₁	F ₂	F ₃	F ₄	F ₅	F ₆
\otimes	50	34.1	18.3	65.9	0	76.6	88.1	76.6	18.3	0	101.6	101.6	0	34.1	50
\heartsuit	14.3	55.6	14.3	55.6	34.9	15.9	57.2	0	69.9	0	0	69.9	69.9	-1.6	71.5
Ø	201)	201)	201)	20 ¹⁾	6.3	6.3	6.3	4	4	M10 ²⁾	M10 ²⁾	M10 ²⁾	M10 ²⁾	M 6 ²⁾	M 6 ²⁾

NG 25 - ISO 4401



	P	A	T	В	L	Х	Y	G ₁	G2	F ₁	F ₂	F ₃	F ₄	F ₅	F ₆
\otimes	77	53.2	29.4	100.8	5.6	17.5	112.7	94.5	29.4	0	130.2	130.2	0	53.2	77
\heartsuit	17.5	74.6	17.5	74.6	46	73	19	-4.8	92.1	0	0	92.1	92.1	0	92.1
Ø	25 ¹⁾	25 ¹⁾	25 ¹⁾	25 ¹⁾	11.2	11.2	11.2	7.5	7.5	M12 ²⁾					

Bosch Rexroth AG Industrial Hydraulics

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